A review of the stellarator concept



Princeton Science Action (2013)

PPPL internship (2013)

Princeton A.B. Astrophysical Sciences (2011-2015)

UMD Ph.D. Physics (2015-2020)

Outline

- Magnetic confinement without symmetry
- Ingredients of stellarator confinement
- How do we "cook" a stellarator?
- Stellarators in context

Single particle motion Review: [Hussein Day 2]

Straight field provides perpendicular confinement

Single particle motion Review: [Hussein Day 2]

Straight field provides perpendicular confinement

Avoid end losses!

$$B \sim 1/R$$

The solution: rotational transform

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$$\iota = \frac{\# \text{ poloidal turns}}{\# \text{ toroidal turns}} = \frac{1}{q}$$

"rotational transform"

"safety factor"

$$\iota = 3/2$$

The solution: rotational transform

"rotational transform"

"safety factor"

Trapped particles and drifts

Trapped particles and drifts

Trapped particles and drifts

Trapped particles and drifts

What about orbits in a stellarator?

Generating rotational transform

Expansion near the magnetic axis $\iota = \frac{1}{2\pi} \int_0^L \frac{\left[\frac{\mu_0 J}{2B_0} - (\cosh \eta - 1)\delta' - \tau\right] dl}{\cosh \eta} - N$

Generating rotational transform

Generating rotational transform

Large Helical Device

Generating rotational transform

Spitzer's figure-eight

Expansion near the magnetic axis

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The zoology of particle orbits in 3D fields

Perturbed tokamak

ripple trapped

D.A. Spong et al, APS DPP (2014).

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Perturbed tokamak

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The zoology of particle orbits in 3D fields

D.A. Spong et al, APS DPP (2014).

ripple trapped

Collisionless guiding center confinement

$$\mathcal{L}(\boldsymbol{x}, \dot{\boldsymbol{x}}) = m \frac{|\dot{\boldsymbol{x}}|^2}{2} + q \boldsymbol{A}(\boldsymbol{x}) \cdot \dot{\boldsymbol{x}}$$

Average over fast gyration

 $\mathcal{L}(\psi,\theta,\phi,\dot{\psi},\dot{\theta},\dot{\phi}) = \mathcal{L}(\psi,\frac{B(\psi,\theta,\phi)}{\psi},\dot{\psi},\dot{\theta},\dot{\phi})$

Collisionless guiding center confinement - Axisymmetry

$$\frac{\partial B}{\partial \phi} = 0 \to \frac{dp_{\phi}}{dt} = 0$$

$$p_{\phi} = mRv_{\phi} + qRA_{\phi}$$

 $\mathcal{L}($

Collisionless guiding center confinement - Axisymmetry

$$\frac{\partial B}{\partial \phi} = 0 \rightarrow \frac{dp_{\phi}}{dt} = 0$$
$$p_{\phi} = m R v_{\phi} + q R A_{\phi}$$

Const. on ψ surfaces

Magnetic surface Trapped orbit

Collisionless guiding center confinement - Quasisymmetry

$$\eta = M\theta - N\phi$$
$$\chi = M'\theta - N'\phi$$

$$\frac{\partial B}{\partial \eta} = 0 \to \frac{dp_{\eta}}{dt} = 0$$

$$p_{\eta} = mv_{\eta} + qF(\psi)$$

Collisionless guiding center confinement - Quasisymmetry

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$$\eta = M\theta - N\phi$$
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$$\frac{\partial B}{\partial \eta} = 0 \to \frac{dp_{\eta}}{dt} = 0$$

Const. on ψ surfaces

What does this look like?

Quasi-poloidal symmetry – Quasi-Poloidal Stellarator (QPS)

 $\eta = M\theta - N\phi$

$$\frac{\partial B}{\partial \theta} \approx 0 \rightarrow \frac{d p_\theta}{d t} \approx 0$$

D.A. Spong et al, IAEA (2003).

B on ψ surface

Ф

Quasi-helical symmetry – Helically Symmetric eXperiment (HSX)

$$\frac{\partial B}{\partial \eta} \approx 0 \to \frac{dp_{\eta}}{dt} \approx 0 \qquad \eta = \theta - \phi$$

Quasi-axisymmetry – National Compact Stellarator eXperiment (NCSX)

 $\eta = M\theta - N\phi$

B on ψ surface

Collisionless guiding center confinement - Omnigeneity

 $H(p,q,\lambda) \rightarrow$ Hamiltonian depending on slowly varying parameter $\frac{\lambda}{\lambda} \ll \omega \rightarrow$ parameters varying slowly in comparison with frequency

 $J(H, \lambda) = \oint p(H, q, \lambda) dq$ = adiabatic invariant is conserved

Collisionless guiding center confinement - Omnigeneity

 $H(p,q,\lambda) \rightarrow$ Hamiltonian depending on slowly varying parameter $\frac{\lambda}{\lambda} \ll \omega \rightarrow$ parameters varying slowly in comparison with frequency

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Recall - Magnetic moment conservation

Assuming $\dot{B}/B \ll \Omega$, $J = \oint p_{\theta} d\theta = \oint m v_{\perp} \rho \ d\theta = \left(\frac{4\pi \ m}{q}\right) \frac{m v_{\perp}^2}{2B} = \text{const.}$

 $\mu =$ "magnetic moment"

Collisionless guiding center confinement - Omnigeneity

Trapped orbit

D.A. Spong et al, IAEA (2003).

Assuming drift frequency << bounce frequency,

$$J_{||}(\psi, \alpha, E, \mu) = \oint dl \, v_{||}(\psi, \alpha, E, \mu) = \text{const.}$$

"parallel adiabatic invariant"

Collisionless guiding center confinement - Omnigeneity

Trapped orbit

D.A. Spong et al, IAEA (2003).

$$\frac{\partial J_{||}}{\partial \alpha} = 0 \rightarrow \text{"omnigeneity"}$$

Assuming drift frequency << bounce frequency,

$$J_{||}(\psi, \alpha, E, \mu) = \oint dl \, v_{||}(\psi, \alpha, E, \mu) = \text{const.}$$

"parallel adiabatic invariant"

Collisionless guiding center confinement - Omnigeneity

Far from omnigeneous

Close to omnigeneous

H. Yamaguchi, Nuclear Fusion 59 (2019).

Collisionless guiding center confinement - Omnigeneity

Collisional guiding center confinement

Collisional guiding center confinement [Parra Day 3]

Magnetic field integrability

NCSX Modular Coils

D. Strickler et al, IAEA (2004).

Magnetic field integrability

NCSX Modular Coils

Magnetic field integrability – Hamiltonian nature of field line flow

 $A(\psi_T, \theta, \phi) = \psi_T \nabla \theta - \psi_P(\psi_T, \theta, \phi) \nabla \phi$ $B(\psi_T, \theta, \phi) = \nabla \psi_T \times \nabla \theta - \nabla \psi_P \times \nabla \phi$

Magnetic field integrability – Hamiltonian nature of field line flow

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$$\frac{d\theta}{d\phi} = \frac{\boldsymbol{B} \cdot \nabla \theta}{\boldsymbol{B} \cdot \nabla \phi} = \frac{\partial \psi_P}{\partial \psi_T}$$
$$\frac{d\psi_T}{d\phi} = \frac{\boldsymbol{B} \cdot \nabla \psi_T}{\boldsymbol{B} \cdot \nabla \phi} = -\frac{\partial \psi_P}{\partial \theta}$$

Hamiltonian $\rightarrow \psi_P$ coordinate $\rightarrow \theta$ momentum $\rightarrow \psi_T$ time $\rightarrow \phi$

Magnetic field integrability – Hamiltonian nature of field line flow

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$$\frac{d\theta}{d\phi} = \frac{\boldsymbol{B} \cdot \nabla \theta}{\boldsymbol{B} \cdot \nabla \phi} = \frac{\partial \psi_P}{\partial \psi_T}$$
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Hamiltonian $\Rightarrow \psi_P$ coordinate $\Rightarrow \theta$ momentum $\Rightarrow \psi_T$ time $\Rightarrow \phi$

$$\frac{\partial \psi_P(\theta, \psi_T, \phi)}{\partial \phi} = 0 \rightarrow \text{integrability}$$
$$\boldsymbol{B} \cdot \nabla \psi_p = 0 \text{ [i.e., } \psi_p \text{ is flux label]}$$

Magnetic field integrability – Hamiltonian nature of field line flow

$$B(\psi_T, \theta, \phi) = \nabla \psi_T \times \nabla \theta - \nabla \psi_P \times \nabla \phi$$
$$\psi_P = \frac{1}{2} \psi_T^2 + \epsilon \cos(\theta - \phi)$$
Integrable Non-integrable

Magnetic field integrability – Hamiltonian nature of field line flow

$$B(\psi_T, \theta, \phi) = \nabla \psi_T \times \nabla \theta - \nabla \psi_P \times \nabla \phi$$
$$\psi_P = \frac{1}{2} \psi_T^2 + \epsilon \left[\cos(4\theta - \phi) + \cos(4\theta - 2\phi) + \cos(4\theta - 3\phi) \right]$$
Integrable Non-integrable

...and many more

- ✓MHD stability
- ✓ Collisional "bootstrap" current
- ✓ Energetic particle confinement
- ✓ Equilibrium β limit
- ✓ Divertor configuration
- ✓ Reduction of turbulent transport
- ✓ Coil feasibility

...and many more

- ✓MHD stability
- ✓ Collisional "bootstrap" current
- ✓ Energetic particle confinement ✓ Equilibrium β limit
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ASG Superconductors

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How do we "cook" a stellarator?

MHD equilibrium optimization Review: [Wright Day 3]

$$(\nabla \times B) \times B = \mu_0 \nabla p$$
 in V_{plasma}
 $\nabla \cdot B = 0$ in V_{plasma}
 $B \cdot \hat{n} = 0$ on S_{plasma}
Given $p(\psi)$, $I_T(\psi)$

$$\min_{S_{\text{plasma}}} f(\boldsymbol{B}(S_{\text{plasma}}), S_{\text{plasma}})$$

How do we "cook" a stellarator?

MHD equilibrium optimization Review: [Wright Day 3]

How do we "cook" a stellarator? Coil optimization

Total normal field to plasma boundary

$$\boldsymbol{B}(\boldsymbol{x}) \cdot \boldsymbol{\widehat{n}}(\boldsymbol{x}) = \boldsymbol{B}_{P}(\boldsymbol{x}) \cdot \boldsymbol{\widehat{n}}(\boldsymbol{x}) + \frac{\mu_{0}}{4\pi} \int_{\mathbb{R}^{3} \setminus V_{\text{plasma}}} d^{3}\boldsymbol{x}' \frac{\boldsymbol{J}_{C}(\boldsymbol{x}') \times (\boldsymbol{x} - \boldsymbol{x}') \cdot \boldsymbol{\widehat{n}}(\boldsymbol{x})}{|\boldsymbol{x} - \boldsymbol{x}'|^{3}}$$

$$\min_{J_{C}} \left(\int_{S_{\text{plasma}}} d^{2}x \left(\boldsymbol{B} \cdot \widehat{\boldsymbol{n}} \right)^{2} + (\text{coil complexity}) \right)$$

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The result of optimization

D.A. Spong et al, APS DPP (2014).

The result of optimization – Wendelstein 7-X

The result of optimization – Wendelstein 7-X

"Not optimized" (scaled to W7-X)

T. Sunn Pedersen et al, IAEA (2021).

Comparison with tokamak performance

Overview of stellarators & tokamaks

Tokamaks

- ✓ Automatic guiding center confinement
- ✓ Automatic integrability
- ✓ Simpler design
- × Requires large plasma current
- **X** Steady-state is challenging/inefficient

Stellarators

- × Confinement optimization required
- × Shaping by complicated coils/magnets
- ✓ Low recirculating power
- ✓ No plasma-terminating disruptions
- ✓ No Greenwald density limit

Plasma Phys. Control. Fusion 54 (2012) 124009 (12pp)

doi:10.1088/0741-3335/54/12/124009

Stellarator and tokamak plasmas: a comparison

P Helander, C D Beidler, T M Bird, M Drevlak, Y Feng, R Hatzky, F Jenko, R Kleiber, J H E Proll, Yu Turkin and P Xanthopoulos

Max-Planck-Institut für Plasmaphysik, Greifswald and Garching, Germany

Open questions and new frontiers

Can we optimize stellarators for reduced turbulence?

J. Alucon et al, *PPCF* 62 (2020).

Can we confine stellarators with permanent magnets?

C. Zhu et al, Nuclear Fusion, 60 (2020).

Why can stellarators routinely violate linear MHD stability limits?

A. Weller et al, Fusion Science & Tech., 50 (2006).

An introduction to stellarators: from magnetic fields to symmetries and optimization (arxiv:1908.05360)

- 1. Introduction
- 2. Background
- 3. Electric and magnetic fields: Maxwell's equations
- 4. Classical mechanics
- 5. Single particle motion in electromagnetic fields
- 6. Coordinate systems
- 7. Toroidal magnetic confinement
- 8. Coupling of particles and electromagnetic fields: MHD models
- 9. Magnetic coordinates
- 10. Challenges associated with 3D equilibrium fields
- 11. Models of 3D equilibrium magnetic fields
- 12. Symmetries in stellarators
- 13. Optimization for stellarator design
- 14. New frontiers of optimization

	MHD equilibrium	Force-free fields	Vacuum fields
	(surfaces assumed)		
Hyp.	$oldsymbol{J} imes oldsymbol{B} eq 0$	$oldsymbol{J} imes oldsymbol{B} = 0$	$oldsymbol{J}=0$
	abla p eq 0	$\nabla p = 0$ and $\lambda = \text{const.}$	abla p=0
	$oldsymbol{J} imes oldsymbol{B} = abla p$	$ abla imes oldsymbol{B} = \lambda oldsymbol{B}$	$\Delta \widetilde{\Phi}_B = 0$
PDE	$ abla \cdot \boldsymbol{B} = 0$		
model	$\mu_0 oldsymbol{J} = abla imes oldsymbol{B}$	$\mu_0 oldsymbol{J} = abla imes oldsymbol{B}$	
Given	$p(\psi),\iota(\psi),\Psi_T$	λ, Ψ_T	I_P
Unkn.	В	В	$\widetilde{\Phi}_B$
With	$oldsymbol{J}$ function of $oldsymbol{B}$	$oldsymbol{J}$ function of $oldsymbol{B}$	$oldsymbol{B} = abla \Big(\widetilde{\Phi}_B + \left(\mu_0 I_P / 2 \pi ight) \phi \Big)$
BC	$oldsymbol{B}\cdot\hat{oldsymbol{n}}=0$	$oldsymbol{B}\cdot\hat{oldsymbol{n}}=0$	$\hat{m{n}}\cdot abla \widetilde{\Phi}_B + \left(\mu_0 I_P/2\pi ight) \hat{m{n}}\cdot abla \phi = m{B}\cdot \hat{m{n}}$

Thank you, SULI!