

Simulation of Collisions in Slab Geometry Approximation of Wave Driven Rotating Torus (WDRT)



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Algorithm Development

Boris Algorithm

- Conserves volume in phase space^[2]
- Designed for charged particles
- Offset computation of velocity and position

$$\boldsymbol{v}^{-} = \boldsymbol{v}_{k} + \frac{q}{m} \boldsymbol{E}_{k} \frac{\Delta t}{2}$$
$$\boldsymbol{v}^{+} - \boldsymbol{v}^{-} \qquad q \qquad (+, +, -) \in \mathbf{P}$$

$$\frac{\Delta t}{\Delta t} = \frac{q}{2m} (\boldsymbol{v}^+ + \boldsymbol{v}^-) \times \boldsymbol{B}_k$$
$$\boldsymbol{w}_{k+1} = \boldsymbol{w}^+ + \frac{q}{2m} \boldsymbol{F}_k \frac{\Delta t}{m}$$

$$\boldsymbol{v}_{k+1} = \boldsymbol{v}^+ + \frac{1}{m}\boldsymbol{E}_k \frac{1}{2}$$

Dynamic Time Step

- Want time step to be small compared to gyro-period, therefore scale negatively with magnetic field strength
- More difficult to implement in Boris Algorithm^[3]
- $dt = dt_0 ({}^{B_0}/_B)$

Magnetic field strength (red) and time step (blue) for each step



Langevin Model for Collisions

Simulations of WDRT





Standard approximation for collisions impact on single particle trajectories^[4]

 $m\frac{d\boldsymbol{v}}{dt} = q(\boldsymbol{E} + \boldsymbol{v} \times \boldsymbol{B}) - \gamma(\boldsymbol{v} - \boldsymbol{v}_{\boldsymbol{E} \times \boldsymbol{B}}) + \boldsymbol{L}(t)$ $\langle L_i(t)L_j(t')\rangle = 2\gamma k_B T \delta_{ij}\delta(t-t')$

• Where L(t) is a multivariate Gaussian • We want collision time greater than traversal time

 $\gamma = 0.1 \times v_{E \times B}/L$

Application of Algorithm

• Predicts the trajectory of particles • Can track the evolution of a random distribution of initial conditions













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clusions/Further Research

ilon dependence





nparison to fluid-like model

 $\gamma = 10 \times v_{E \times B} / L$



nperature Anisotropy

Parallel and Perpendicular velocities evolve differently

References

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