# Computational Methods in Plasma Physics 

Richard Fitzpatrick<br>Institute for Fusion Studies<br>University of Texas at Austin

## Purpose of Talk

- Describe use of numerical methods to solve simple problem in plasma physics that, nevertheless, cannot be solved via standard analytic methods.


## Plasma Physics Problem

- Collisionless, unmagnetized, 1D (i.e., $\partial / \partial y=0, \partial / \partial z=0$ ) plasma consisting of N electrons and N singly-charged ions.
- lons much more massive than electrons, so on sufficiently short time-scales can treat ions as static, uniform, neutralizing background, and only consider motion of electrons.
- Initial state: Two counter-propagating warm electron beams.
- If beam speed significantly larger than thermal speed then system unstable to two-stream instability (see Wikipedia page).
- At small perturbation amplitudes, two-stream instability can be treated analytically. At large perturbation amplitudes, analytic methods break down, necessitating numerical approach.


## Electron Equations of Motion

- Let $r_{i}$ be $x$-coordinate of $i$ th electron. Equations of motion of $i t h$ electron are

$$
\begin{aligned}
& \frac{d r_{i}}{d t}=v_{i}, \\
& \frac{d \nu_{i}}{d t}=-\frac{e}{m_{e}} E\left(r_{i}\right),
\end{aligned}
$$

where $e>0$ is magnitude of electron charge, $m_{e}$ is electron mass, and $E(x)$ is $x$-component of electric field-strength at position $x$.

- N.B. 1D nature of problem implies that mode is longitudinal: i.e., $\mathbf{k} \propto \mathbf{E}$. Longitudinal plasma modes do not self-generate magnetic fields. Hence, absence of magnetic term in equations of motion.


## Poisson's Equation

- Electric field-strength expressed in terms of scalar potential,

$$
E(x)=-\frac{d \phi}{d x} .
$$

- Poisson-Maxwell equation yields

$$
\frac{d^{2} \phi}{d x^{2}}=-\frac{e}{\epsilon_{0}}\left[n_{0}-n(x)\right]
$$

where $\epsilon_{0}$ is permittivity of free-space, $\mathfrak{n}(x)$ is electron number density [i.e., number of electrons in interval $x$ to $x+d x$ is $n(x) d x]$, and $n_{0}$ is uniform ion number density.

- Spatial average of $n(x)$ equal to $n_{0}$, since equal numbers of ions and electrons.


## Initial State

- Initial electron distribution function consists of two counterpropagating Maxwellian beams of mean speed $\nu_{\mathrm{b}}$ and thermal spread $\nu_{\mathrm{t}}$ : i.e.,

$$
f(x, v)=\frac{\mathfrak{n}_{0}}{2}\left[\frac{1}{\sqrt{2 \pi} v_{\mathrm{t}}} \mathrm{e}^{-\left(v-v_{\mathrm{b}}\right)^{2} /\left(2 v_{\mathrm{t}}^{2}\right)}+\frac{1}{\sqrt{2 \pi} v_{\mathrm{t}}} \mathrm{e}^{-\left(v+v_{\mathrm{b}}\right)^{2} /\left(2 v_{\mathrm{t}}^{2}\right)}\right] .
$$

- $f(x, v) d x d v$ is probable number of electrons between $x$ and $x+d x$ with velocities in range $v$ to $v+d v$.
- Beam temperature, $T$, related to thermal spread via $\nu_{t}=\sqrt{T / m_{e}}$, where $T$ measured in energy units.


## Normalization

- First step in solving physics problem numerically is to normalize governing equations: i.e., render all variables dimensionless, and as many as possible $\mathcal{O}(1)$.
- Normalization reduces likelihood of arithmetic underflow and overflow.
- Normalization facilities identification of terms in governing equations that can be safely neglected (such terms having magnitudes much less than unity).


## Normalization Scheme

- All times expressed in units of $\omega_{p}^{-1}$, where

$$
\omega_{p}=\sqrt{\frac{n_{0} e^{2}}{\epsilon_{0} m_{e}}}
$$

is electron plasma frequency: i.e., typical frequency of electrostatic electron oscillations.

- All lengths expressed in units of Debye length,

$$
\lambda_{\mathrm{D}}=\frac{v_{\mathrm{t}}}{\omega_{\mathrm{p}}}:
$$

i.e., typical length-scale above which electrons exhibit collective (i.e., plasma-like) effects, instead of acting like individual particles.

## Normalized Equations

- Normalized electron equations of motion:

$$
\begin{aligned}
\frac{d r_{i}}{d t} & =v_{i} \\
\frac{d v_{i}}{d t} & =-E\left(r_{i}\right) \\
E(x) & =-\frac{d \phi}{d x} \\
\frac{d^{2} \phi}{d x^{2}} & =\frac{n(x)}{n_{0}}-1
\end{aligned}
$$

- Normalized initial distribution function:

$$
f(x, v)=\frac{\mathfrak{n}_{0}}{2}\left[\frac{1}{\sqrt{2 \pi}} \mathrm{e}^{-\left(v-v_{\mathrm{b}}\right)^{2} / 2}+\frac{1}{\sqrt{2 \pi}} \mathrm{e}^{-\left(v+v_{\mathrm{b}}\right)^{2} / 2}\right]
$$

## Spatial Domain of Solution

- Equations solved in spatial domain

$$
0 \leq x \leq \mathrm{L}
$$

where $L \gg 1$ : i.e., plasma many Debye lengths in extent.

- For sake of simplicity, adopt periodic boundary conditions: i.e., identify left and right boundaries of solution domain.
- Follows that $n(0)=n(L), E(0)=E(L), \phi(0)=\phi(L)$ at all times.
- Electrons that cross right boundary of solution domain must reappear at left boundary with same velocity, and vice versa.


## Spatial Discretization

- Define set of J equally-spaced spatial grid points located at coordinates

$$
x_{j}=j \delta x,
$$

for $\mathrm{j}=0$ to $\mathrm{J}-1$, where $\delta \mathrm{x}=\mathrm{L} / \mathrm{J}$.

- Let

$$
\begin{aligned}
n_{j} & =\mathfrak{n}\left(x_{j}\right), \\
\phi_{\mathfrak{j}} & =\phi\left(x_{\mathfrak{j}}\right)
\end{aligned}
$$

et cetera.

## Evaluation of Electron Number Density - I

- Electron number density at grid points calculated from electron coordinates via particle-in-cell (PIC) approach.
- Suppose ith electron lies between $j$ th and $(j+1)$ th grid points: i.e., $x_{j}<r_{i}<x_{j+1}$. Let

$$
\begin{aligned}
n_{j} & \rightarrow n_{j}+\left(\frac{x_{j+1}-r_{i}}{x_{j+1}-x_{j}}\right) / \delta x, \\
n_{j+1} & \rightarrow n_{j+1}+\left(\frac{r_{i}-x_{j}}{x_{j+1}-x_{j}}\right) / \delta x .
\end{aligned}
$$

Thus, $n_{j} \delta x$ increases by 1 if electron at $j$ th grid point, $n_{j+1} \delta x$ increases by 1 if electron at $(j+1)$ th grid point, $n_{j} \delta x$ and $n_{j+1} \delta x$ both increase by $1 / 2$ if electron halfway between grid points, et cetera.

## Evaluation of Electron Number Density - II

- Performing analogous assignment for each electron, in turn, allows the $n_{j}$ to be determined from the $r_{i}$ (assuming that all the $n_{j}$ initialized to zero at start of process).
- Clear that

$$
\int_{0}^{L} n(x) d x \simeq \sum_{j=0, J-1} n_{j} \delta x=N
$$

as must be the case if the system contains N electrons.

- Relative error in calculation of the $n_{j}$ from the $r_{i}$ is $\mathcal{O}\left(1 / \mathrm{J}^{2}\right)$.


## Fourier Solution of Poisson's Equation - I

- Poisson's equation (n.b., $n_{0}=N / L$ in normalized units):

$$
\begin{aligned}
& \frac{d^{2} \phi}{d x^{2}}=\rho(x) \\
& \rho(x)=\mathfrak{n}(x) / n_{0}-1
\end{aligned}
$$

- Let

$$
\begin{aligned}
\phi_{j} & =\sum_{j^{\prime}=0, \mathrm{~J}-1} \bar{\phi}_{j^{\prime}} \mathrm{e}^{\mathrm{ij} j^{\prime} 2 \pi / \mathrm{J}} \\
\rho_{j} & =\sum_{j^{\prime}=0, \mathrm{~J}-1} \bar{\rho}_{j^{\prime}} \mathrm{e}^{\mathrm{ij} j^{\prime} 2 \pi / \mathrm{J}}
\end{aligned}
$$

for $j=0$ to $\mathrm{J}-1$, which automatically satisfies periodic boundary conditions $\phi_{\mathrm{J}}=\phi_{0}$ and $\rho_{\mathrm{J}}=\rho_{0}$.

## Fourier Solution of Poisson's Equation - II

- $\bar{\rho}_{0}=\int_{0}^{L} \rho(x) d x / L=0$, because $\int_{0}^{L} n(x) d x / L=n_{0}$.
- Remaining $\rho_{j}$ obtained via standard Fourier inversion theorem:

$$
\bar{\rho}_{j}=J^{-1} \sum_{j^{\prime}=0, J-1} \rho_{j^{\prime}} e^{-i j j^{\prime} 2 \pi / J}
$$

- Fourier inversion of Poisson's equation yields: $\bar{\phi}_{0}=0$, and

$$
\bar{\phi}_{j}=-\bar{\rho}_{j} /\left[j^{2}(2 \pi / L)^{2}\right]
$$

for $j=1$ to $J / 2$.

- Also,

$$
\bar{\phi}_{j}=\bar{\phi}_{J-j}^{*}
$$

for $j=J / 2+1$ to $J-1$, which ensures that $\phi_{j}$ are real.

## Calculation of $E_{j}$

- Electric field at grid points:

$$
\mathrm{E}_{j}=\frac{\phi_{j-1}-\phi_{j+1}}{2 \delta x},
$$

for $\mathrm{j}=0$ to $\mathrm{J}-1$.

- $N . B . j=0$ and $\mathfrak{j}=\mathrm{J}-1$ are special cases that are resolved using periodic boundary conditions.
- Relative error in above first-order discretization scheme is $\mathcal{O}\left(1 / \mathrm{J}^{2}\right)$.


## Calculation of $E\left(r_{i}\right)$

- Suppose that $\mathrm{r}_{\mathrm{i}}$ lies between j th and $(\mathrm{j}+1)$ th grid points: i.e., $x_{j}<r_{i}<x_{j+1}$.
- Linear interpolation:

$$
E\left(r_{i}\right)=\left(\frac{x_{j+1}-r_{i}}{x_{j+1}-x_{j}}\right) E_{j}+\left(\frac{r_{i}-x_{j}}{x_{j+1}-x_{j}}\right) E_{j+1} .
$$

- Relative error in interpolation scheme is $\mathcal{O}\left(1 / \mathrm{J}^{2}\right)$.


## Fast Fourier Transform

- Discrete Fourier transform (DFT) is computationally expensive because of large number of trigonometric function evaluations.
- DFT typically require $\mathcal{O}\left(\mathrm{J}^{2}\right)$ arithmetic operations.
- Fast Fourier transform (FFT) algorithm (see Wikipedia page) rapidly computes DFT via factorization.
- FFT only requires $\mathcal{O}(\mathrm{J} \ln \mathrm{J})$ arithmetic operations.
- Since $J=1000$ in program, use of FFT algorithm implies reduction in arithmetic operations per time-step by factor of 100 .
- Program implements FFT algorithm via calls to fftw library. ${ }^{\text {a }}$

[^0]
## Euler Method

- Suppose that function $y(t)$ satisfies first-order ordinary differential equation (ODE)

$$
\frac{d y}{d t}=f[y(t)] .
$$

- Equation can be solved numerically via repeated use of Euler method (see Wikipedia page):

$$
y(t+h)=y(t)+h f[y(t)]+\mathcal{O}\left(h^{2}\right)
$$

- Truncation error per time-step is $\mathcal{O}\left(h^{2}\right)$, necessitating relatively small time-steps to keep overall truncation error to acceptable levels.
- Generalization to system of N coupled first-order ODEs straightforward.


## Fourth-Order Runge-Kutta Method

- Fourth-order Runge-Kutta (RK4) method (see Wikipedia page):

$$
\begin{aligned}
k_{1} & =h f[y(t)] \\
k_{2} & =h f\left[y(t)+k_{1} / 2\right] \\
k_{3} & =h f\left[y(t)+k_{2} / 2\right], \\
k_{4} & =h f\left[y(t)+k_{3}\right], \\
y(t+h) & =y(t)+k_{1} / 6+k_{2} / 3+k_{3} / 3+k_{4} / 6+\mathcal{O}\left(h^{5}\right)
\end{aligned}
$$

- Algorithm requires approximately 3 times number of arithmetic operations per time-step as Euler method. However, truncation error per time-step much smaller $\left[\mathcal{O}\left(h^{5}\right)\right.$ rather than $\left.\mathcal{O}\left(h^{2}\right)\right]$.
- Can take much larger time-steps using RK4 method. More than makes up for factor of 3 increase in operations per time-step.


## Program Pic

- Program Pic ${ }^{\text {a }}$ is PIC code (which implements previously described calculation) written in $\mathrm{C}++$ language.
- Program uses RK4 algorithm to integrate electron equations of motion. At each time-step, Poisson's equation solved via calls to fftw library.
- Default program parameters: $\mathrm{N}=20,000, \mathrm{~L}=100, \nu_{\mathrm{b}}=3$, $J=1000, h=0.1$.

[^1]Initial State: $\mathrm{t}=0$


Final State: $t=50$


## Visualization

- Phase-space motion of electrons visualized as follows:
- Program writes electron phase-space coordinates to file at each time-step (with separate file for each time-step).
- Python ${ }^{\text {a }}$ script reads coordinate files and employs Matplotlib ${ }^{\text {b }}$ package to produce separate png plot of electron phase-space positions at each time-step.
- Finally, Python script calls ImageMagick ${ }^{\mathrm{c}}$ image processing application to combine separate png plots into animated gif. (Animated gifs can be viewed by all modern web-browsers.)

[^2]
## Energy Conservation

- Only force in problem (self-generated electric field) is conservative. So, total system energy should be constant of motion.
- (Normalized) total system energy:

$$
\mathcal{E}=\mathrm{K}+\mathrm{U},
$$

where

$$
K=\sum_{i=1, N} v_{i}^{2} / 2
$$

is kinetic energy of electrons, and energy stored in electric field is

$$
U=\frac{n_{0}}{2} \int_{0}^{L} E^{2}(x) d x=-\frac{1}{2} \int_{0}^{L} n(x) \phi(x) d x=-\sum_{i=1, N} \phi\left(r_{i}\right) / 2
$$

## Test of Energy Conservation



Blue curve is $\mathcal{E} / \mathrm{N}$. Red curve is $\mathrm{K} / \mathrm{N}$.

## Entropy Conservation

- Motion of electrons in self-generated electric field should be reversible in time: i.e., if we take final state, reverse velocities of all electrons, and evolve system forward in time by same amount, then should recover initial state (with reversed velocities).
- Equivalent to saying total entropy of system is constant of motion.

Initial State: $\mathrm{t}=0$


Final State: $\mathrm{t}=50$


## Using PIC Code to Simulate Real Plasma

- Real plasmas typically consist of $N_{A} \sim 10^{24}$ electrons. This is far greater number than could ever be accommodated in PIC code.
- Particle motion in PIC code only depends on charge-to-mass ratio. Could identify particles in PIC code as super-particles consisting of correlated clumps of real particles.
- Alternatively, could identify particles in PIC code as markers used to reconstruct electron distribution function, $f(x, v, t)$, at each time-step, in much same manner as electron number density, $\mathfrak{n}(x)$, reconstructed from electron coordinates in code. Hence, PIC code effectively evolving Vlasov equation:

$$
\frac{\partial f}{\partial t}+v \frac{\partial f}{\partial x}-\frac{e E(x)}{m_{e}} \frac{\partial f}{\partial v}=0
$$

## Statistical Noise in PIC Codes

- PIC codes suffer from statistical noise. If phase-space binned into regions of 'volume' $d x d v$ then distribution function in given bin has irreducible statistical variation of relative magnitude $1 / \sqrt{N_{\text {bin }}}$, where $\mathrm{N}_{\text {bin }}$ is typical number of electrons in each bin.
- In 1D (1 space dimension, 1 velocity dimension), with $100 \times 100$ bins in phase-space, keeping statistical noise below $1 \%$ requires $100 \times 100 \times 100^{2}=10^{8}$ electrons.
- In 2D, (2 space dimensions, 2 velocity dimensions), with $100^{2} \times 100^{2}$ bins in phase-space, keeping statistical noise below $1 \%$ requires $100^{2} \times 100^{2} \times 100^{2}=10^{12}$ electrons.
- In 3D, (3 space dimensions, 3 velocity dimensions), with $100^{3} \times 100^{3}$ bins in phase-space, keeping statistical noise below $1 \%$ requires $100^{3} \times 100^{3} \times 100^{2}=10^{16}$ electrons!


## Continuum Codes

- Alternative to PIC approach is to solve Vlasov equation,

$$
\frac{\partial f}{\partial t}+v \frac{\partial f}{\partial x}-\frac{e E(x)}{m_{e}} \frac{\partial f}{\partial v}=0
$$

directly, using analogous methods to those typically used to solve fluid codes.

- Main advantage of so-called continuum codes is absence of statistical noise. Disadvantage is that numerical algorithms used in continuum codes more complicated that those used in PIC codes. Also, continuum codes harder to parallelize that PIC codes.


## Scientific Computation Resources

- Scientific computation course: http://farside.ph.utexas.edu.
- Gnu Scientific Library (GSL). ${ }^{\text {a }}$ Free (!) C library of numerical routines for scientific computation. Includes special functions, linear algebra, eigensystems, adapative integration of odes, etc.
- Matplotlib. ${ }^{\text {b }}$ Free python 2D plotting library.
- Maxima. ${ }^{c}$ Free computer algebra system.
- Petsc. ${ }^{d}$ Free suite of data structures and routines for scalable (parallel) solution of partial differential equations.

[^3]
[^0]:    ahttp://www.fftw.org

[^1]:    ${ }^{a}$ http://farside.ph.utexas.edu/teaching/plasma/plasma.html

[^2]:    ${ }^{\text {a }}$ http://www.python.org
    ${ }^{\mathrm{b}}$ http://matplotlib.org
    ${ }^{\text {c }}$ http://www.imagemagick.org

[^3]:    ${ }^{\text {a http://www.gnu.org/software/gsl }}$
    bhttp://matplotlib.org
    ${ }^{c}$ http://maxima.sourceforge.net
    dhttp://www.mcs.anl.gov/petsc

